

AP® Computer Science A 2004 Sample Student Responses

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(a) Write the Robot method forwardMoveBlocked. Method forwardMoveBlocked returns true if the robot has a wall immediately in front of it, so that it cannot move forward. Otherwise, forwardMoveBlocked returns false.

Complete method forwardMoveBlocked below.

- (b) Write the Robot method move. Method move has the robot carry out one move as specified at the beginning of the question. The specification for a move is repeated here for your convenience.
 - 1. If there are any items on the current tile, then one item is removed.
 - 2. If there are more items on the current tile, then the robot remains on the current tile facing the same direction.
 - 3. If there are no more items on the current tile
 - a) if the robot can move forward, it advances to the next tile in the direction that it is facing;
 - b) otherwise, if the robot cannot move forward, it reverses direction and does not change position.

In writing move, you may use any of the other methods in the Robot class. Assume these methods work as specified, regardless of what you wrote in part (a). Solutions that reimplement the functionality provided by these methods, rather than invoking these methods, will not receive full credit.

Complete method move below.

```
// postcondition: one move has been made according to the
 11
                   specifications above and the state of this
 11
                   Robot has been updated
 private void move()
 É
      if (hall [pos] > 0)
           hall [ >05] -= 1;
      if (hall[pos] == 0 #$ forwardNoveBlocked()!= true)
           if (facing Right)
                Pos -= 1;
           elsc
              pos - = 1,
      else if [hall[pos] == 0 Et forward MoveBlocked () == true)
           if (facing Right)
                 facing Right = false;
           eisc
                facing Right = true;
     ż
Ŝ
```

Part (c) begins on page 20.

GO ON TO THE NEXT PAGE.

(c) Write the Robot method clearHall. Method clearHall clears the hallway, repeatedly having this robot make a move until the hallway has no items, and returns the number of moves made.

In the example at the beginning of this problem, clearHall would take the robot through the moves shown and return 9, leaving the robot in the state shown in the final diagram.

In writing clearHall, you may use any of the other methods in the Robot class. Assume these methods work as specified, regardless of what you wrote in parts (a) and (b). Solutions that reimplement the functionality provided by these methods, rather than invoking these methods, will not receive full credit.

Complete method clearHall below.

```
// postcondition: no more items remain in the hallway;
// returns the number of moves made
public int clearHall()

int numMoves = 0,

while (hallsClear()! = true)

i

move();

return numMoves;

feturn numMoves;

}
```

A4 B.

(a) Write the Robot method forwardMoveBlocked. Method forwardMoveBlocked returns true if the robot has a wall immediately in front of it, so that it cannot move forward. Otherwise, forwardMoveBlocked returns false.

Complete method forwardMoveBlocked below.

```
// postcondition: returns true if this Robot has a wall immediately in front of it, so that it cannot move forward; otherwise, returns false private boolean forwardMoveBlocked()

if (facing Right) {
    if pos == hall length()
        return true;
    else return false;

    else if pos == 0
        return true;
    teturn false;

    veturn false;
```

- (b) Write the Robot method move. Method move has the robot carry out one move as specified at the beginning of the question. The specification for a move is repeated here for your convenience.
 - 1. If there are any items on the current tile, then one item is removed.
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Complete method move below.

```
// postcondition: one move has been made according to the specifications above and the state of this Robot has been updated private void move()

if (hall[pos] > 0)

hall[pos] == 0) {

if (forward Mave Blocked ()) {

lacing Right;

else {

else {

less pos--;

}

}
```

Part (c) begins on page 20.

GO ON TO THE NEXT PAGE.

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Complete method clearHall below.

```
// postcondition: no more items remain in the hallway;
returns the number of moves made

public int clearHall()

int count=0;
int num of roys=0;
for (int i=0; i< hall length(); i++)

humof roys += hallij;

while (num of roys >0) {

move();
caunt++;
num of roys=0;
for (int i=0; i< hall length(); i++)

num of roys += hallij;

}

return count;

{
```

A4 C

(a) Write the Robot method forwardMoveBlocked. Method forwardMoveBlocked returns true if the robot has a wall immediately in front of it, so that it cannot move forward. Otherwise, forwardMoveBlocked returns false.

Complete method forwardMoveBlocked below.

```
postcondition: returns true if this Robot has a wall immediately in front of it, so that it cannot move forward; otherwise, returns false private boolean forwardMoveBlocked()

If thall.length -1 == pos - && facingRight)

return frue;

else if tpos == 0 && !facingRight)

return frue;

veturn frue;

veturn frue;
```

- (b) Write the Robot method move. Method move has the robot carry out one move as specified at the beginning of the question. The specification for a move is repeated here for your convenience.
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