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#### **Unit 1: Kinematics**

- Ecological Relationships
  - Vector vs. Scalar: Vectors include directions.
  - Displacement vs. Distance
  - Velocity vs. Speed: Include direction for velocity.
  - Acceleration: (also a vector)
  - Key Equations:
  - $v = v_0 + at$
  - $ullet \Delta x = v_0 t + rac{1}{2}at^2$

  - ullet  $\mathbf{v}^2=\mathbf{v}^2_0+2\mathbf{d}\Delta\mathbf{x}$  ullet  $\Delta x=rac{1}{2}(v_0+v)t$
  - Projectile Motion
  - Position-Time Graphs: Slope = velocity
  - **Velocity-Time Graphs:** Slope = acceleration
  - Acceleration-Time Graphs
  - Gravity: Gravity: g=9.8 m/s<sup>2</sup>

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### **Unit 2: Dynamics**

<ul> <li>Equilibrium: Net force = 0</li> <li>Newton's Laws:</li> <li>1st: Law of Inertia</li> <li>2nd: F = ma</li> <li>3rd: Action-Reaction</li> <li>Friction: Fp = uFn</li> <li>Ramps/Inclined Planes: Free body diagrams</li> <li>Force Body Diagrams</li> <li>Net Force Calculation</li> </ul>
Additional Notes:

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#### **Unit 3: Circular Motion & Gravitation**

- Centripetal Force: Not an actual force, net force  $\,F_c=rac{mv^2}{r}$  Centripetal Acceleration:  $a_c=rac{v^2}{r}$
- Universal Gravitation:  $F=Grac{m_1m_2}{r^2}$
- Uniform Circular Motion: Constant speed
- Gravitational Mass vs. Inertial Mass

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#### **Unit 4: Energy**

• Work: W = FdParallel: (+) Work

• Antiparallel: (-) Work

ullet Energy Types:Kinetic Energy:  $KE=rac{1}{2}mv^2$ 

ullet Potential Energy:  $PE_g=mgh,\ PE_s=rac{1}{2}kx^2$ 

• Mechanical Energy: Sum of kinetic and potential energy

• Power:  $P = \frac{W}{t}$  or P = Fv

Conservation of Energy

• Graphs & Diagrams

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### **Unit 5: Momentum**

• Momentum: p = mv
• Impulse: ΔP = J
Conservation of Momentum
Collisions: Elastic: Kinetic Energy and Momentum conserved
• Inelastic: Momentum conserved
• Center of Mass
Additional Notes:



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### **Unit 6: Simple Harmonic Motion**

- Spring & Pendulum
- Key Relationships:Hooke's Law: F = kx
- Period Equations:Pendulum:  $(T=2\pi\sqrt{rac{L}{g}})$
- Spring:  $(T=2\pi\sqrt{rac{m}{k}})$

## **AP Physics 1: Torque & Rotational Motion**

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• Rotational Kinematics: θ,ω,αSimilar to linear kinematics with rotational symbols

### **Unit 7: Torque & Rotational Motion**

• Torque: t = Iα
• Moment of Inertia: $I = \Sigma mr^2$
• Angular Momentum: L=Iω
Conservation of Angular Momentum
Additional Notes:

